# Numerical Methods I 

Problem Set 8

due in class, November 19, 2003

1. (From SM.) A quadrature formula on the interval $[-1,1]$ uses the quadrature points $x_{0}=-\alpha$ and $x_{1}=\alpha$, where $0<\alpha \leq 1$ :

$$
\int_{-1}^{1} f(x) \mathrm{d} x \approx w_{0} f(-\alpha)+w_{1} f(\alpha)
$$

(a) The formula is required to be exact whenever $f$ is a polynomial of degree 1 . Show that $w_{0}=w_{1}=1$, independent of the value of $\alpha$.
(b) Show that there is one particular value of $\alpha$ for which the formula is exact for all polynomials of degree 2. Find this $\alpha$, and show that, for this value, the formula is also exact for all polynomials of degree 3 .
2. Consider the composite trapezoidal rule for evaluating the integral

$$
\int_{0}^{1} x^{1 / 3} \mathrm{~d} x
$$

(a) Show, by explicit evaluation, that the local error on the interval $[0, h]$ is proportional to $h^{4 / 3}$.
(b) Show that the global error is also proportional to $h^{4 / 3}$.

Hint: Use part (a) on the first partition and one of the standard error estimates on all other partitions.
3. Project: Use the composite trapezoidal rule with $N$ partitions to approximate the integral of $f(x)=\sinh x$ and $g(x)=\cosh x$ on the interval $[-1,1]$. As in Lab 7, generate a doubly logarithmic error plot. Which of the functions is integrated more accurately?
4. Explain the behavior seen in the previous question using the Euler-Maclaurin summation formula.
5. Project: Use Romberg integration to compute the integral of

$$
\begin{gathered}
f(x)=\mathrm{e}^{x} \\
g(x)=\sin 2 \pi x \\
h(x)=x^{1 / 3}
\end{gathered}
$$

on the interval $[0,1]$. Generate a doubly logarithmic error plot and compare with the results from Lab 7.
6. (From SM.) Show that the weights in the Gauss quadrature formula can also be computed via

$$
W_{k}=\int_{a}^{b} w(x) L_{k}(x) \mathrm{d} x
$$

Recall: Gauss quadrature is based on the expression

$$
\int_{a}^{b} w(x) f(x) \mathrm{d} x \approx \sum_{k=0}^{n} W_{k} f\left(x_{k}\right)+\sum_{k=0}^{n} V_{k} f^{\prime}\left(x_{k}\right)
$$

where

$$
\begin{aligned}
W_{k} & =\int_{a}^{b} w(x) H_{k}(x) \mathrm{d} x \\
V_{k} & =\int_{a}^{b} w(x) K_{k}(x) \mathrm{d} x
\end{aligned}
$$

and where $H_{k}$ and $K_{k}$ are the Hermite interpolation basis polynomials, which can be written in terms of the Lagrange interpolation basis polynomials $L_{k}$ as

$$
\begin{aligned}
& H_{k}(x)=L_{k}^{2}(x)\left(1-2 L_{k}^{\prime}\left(x_{k}\right)\left(x-x_{k}\right)\right), \\
& K_{k}(x)=L_{k}^{2}(x)\left(x-x_{k}\right) .
\end{aligned}
$$

The Gauss quadrature points $x_{0}, \ldots, x_{n}$ are chosen such that $V_{k}=0$ for all $k=1, \ldots, n$.

