

Engineering and Science Mathematics 2B

Homework 4

due March 3, 2004, before 12:00

Normal questions and advanced questions (A) are worth 5 points; easy questions (E) are worth 4 points. Complete either the easy, or the advanced version, not both.

1. Consider the vector space of functions that is spanned by the basis

$$B = \{\sin x, \cos x, \sin 2x, \cos 2x\}.$$

Find the matrix representing the derivative operator with respect to the basis B .

2. Recall the definitions of range and kernel of a linear map A on the vector space \mathbb{R}^n :

$$\begin{aligned}\text{Range } A &= \{A\mathbf{x} : \mathbf{x} \in \mathbb{R}^n\} \\ \text{Ker } A &= \{\mathbf{x} \in \mathbb{R}^n : A\mathbf{x} = 0\}\end{aligned}$$

(E) Let

$$A = \begin{pmatrix} -1 & 2 & -2 \\ 1 & 2 & 6 \\ 0 & 1 & 1 \end{pmatrix}$$

Find a basis for Range A and for Ker A .

(A) Prove that $\dim \text{Ker } A + \dim \text{Range } A = n$.

3. Let

$$A = \begin{pmatrix} 2 & 0 & 2 \\ 0 & 2 & 0 \\ -2 & 0 & 2 \end{pmatrix}$$

represent a linear transformation on \mathbb{R}^3 with respect to the standard basis $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$. Find the matrix A' which represents this transformation with respect to the new basis

$$\mathbf{e}'_1 = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \quad \mathbf{e}'_2 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \quad \mathbf{e}'_3 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}.$$

4. Compute the determinant

$$\begin{vmatrix} 1 & 2 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 7 & 3 \\ 0 & 0 & 1 & 1 \end{vmatrix}.$$

5. (E) Use the determinant to test if the matrix

$$A = \begin{pmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 1 & -1 & 1 \end{pmatrix}$$

represents an invertible linear transformation.

(A) Use the definition of the determinant to show that a matrix A is invertible if and only if and only if $\det A \neq 0$.

6. Show that a matrix A is invertible if and only if all the eigenvalues of A are nonzero.

(Recall that λ is an eigenvalue of A and \mathbf{v} is the corresponding eigenvector if $A\mathbf{v} = \lambda\mathbf{v}$.)