

HW6 - Solutions

1a. Let $x = \cos \theta$

$$\Rightarrow T_k(x) = \cos(k\theta)$$

$$= \operatorname{Re} e^{ik\theta}$$

$$= \frac{1}{2} e^{ik\theta} + \frac{1}{2} e^{-ik\theta}$$

Now, $e^{i\theta} = \cos \theta + i \sin \theta$

$$= x + i\sqrt{1-x^2}$$

$$\Rightarrow T_k(x) = \frac{1}{2} (x + i\sqrt{1-x^2})^k + \frac{1}{2} (x - i\sqrt{1-x^2})^k$$

Note: Strictly speaking, the computation is valid only for $x \in [-1, 1]$. However, expanding the result shows that the expression is a polynomial (which is not obvious at first sight) and thus extends to all $x \in \mathbb{R}$.

(b) Defining the spectral condition number $\kappa = \lambda_{\max} / \lambda_{\min}$, we see that

$$\frac{\lambda_{\max} + \lambda_{\min}}{\lambda_{\max} - \lambda_{\min}} = \frac{\kappa + 1}{\kappa - 1} =: x$$

(1)

Therefore,

$$x \pm i\sqrt{1-x^2} = x \pm \sqrt{x^2-1}$$

$$= \frac{\kappa+1}{\kappa-1} \pm \sqrt{\frac{(\kappa+1)^2}{(\kappa-1)^2} - \frac{(\kappa-1)^2}{(\kappa-1)^2}}$$

$$= \frac{(\kappa+1) \pm \sqrt{4\kappa}}{\kappa-1}$$

$$= \frac{(\sqrt{\kappa} \pm 1)^2}{(\sqrt{\kappa}+1)(\sqrt{\kappa}-1)}$$

$$= \frac{\sqrt{\kappa} \pm 1}{\sqrt{\kappa} \mp 1}$$

$$\Rightarrow T_k(x) = \frac{1}{2} \left(\frac{\sqrt{\kappa}+1}{\sqrt{\kappa}-1} \right)^k + \frac{1}{2} \left(\frac{\sqrt{\kappa}-1}{\sqrt{\kappa}+1} \right)^k$$

$$\geq \frac{1}{2} \left(\frac{\sqrt{\kappa}+1}{\sqrt{\kappa}-1} \right)^k$$

$$\Rightarrow \frac{1}{T_k(x)} \leq 2 \left(\frac{\sqrt{\kappa}-1}{\sqrt{\kappa}+1} \right)^k$$

(2)

(4)

2(a) Let v_1, \dots, v_n be an orthonormal basis of eigenvectors of A .

We can thus write the true solution of $Ax = b$ in the form

$$x = \sum_{j=1}^n \alpha_j v_j$$

$$\Rightarrow b = Ax = \sum_{j=1}^n \lambda_j \alpha_j v_j$$

Let $x^i = \sum_{j=1}^n \alpha_j^i v_j$ denote the i -th iterate of

the algorithm, where $\{\alpha_j^i\}$ are chosen arbitrarily.

We compute

$$\begin{aligned} r^i &= b - Ax^i \\ &= \sum_{j=1}^n \lambda_j \alpha_j^i v_j - \sum_{j=1}^n \lambda_j \alpha_j^i v_j \\ &= \sum_{j=1}^n \lambda_j (\alpha_j - \alpha_j^i) v_j \end{aligned}$$

At the i -th step, we pick an eigenvalue λ_i , and compute

$$\begin{aligned} x^{i+1} &= x^i + \frac{r^i}{\lambda_i} \\ &= \sum_{j=1}^n \alpha_j^i v_j + \sum_{j=1}^n (\alpha_j - \alpha_j^i) \frac{\lambda_j}{\lambda_i} v_j \end{aligned}$$

We see that

$$\alpha_j^{i+1} = \alpha_j^i \quad \text{if } \lambda_i = \lambda_j$$
$$\text{or } \alpha_j^{i+1} = \alpha_j^i \quad \text{if } \lambda_i \neq \lambda_j$$

\Rightarrow After all d distinct eigenvalues have been encountered,

we have $\alpha_j^{i+1} = \alpha_j^i$ for all $j=1, \dots, n$.

(b) To get close to the solution after less than d iterations, one should use the eigenvalues in the order that

assures that the error is decreased in all the eigenspaces,

i.e. $\frac{\lambda_i}{\lambda_j}$ should be less than one for those eigenspaces

for which $\alpha_j^i \neq \alpha_j$.

\Rightarrow Take the eigenvalues from large to small.

(c) If rounding error results in $\alpha_j^i \neq \alpha_j$ although the corresponding eigenvalue λ_j has already been used, then this error will be amplified by a factor $\frac{\lambda_j}{\lambda_i}$ in each subsequent iteration.

(d) To minimize rounding errors, we have to insure that

$$\frac{\lambda_j}{\lambda_i} < 1 \quad \text{for eigenspaces for which } \alpha_j^i \neq \alpha_j.$$

\Rightarrow Take eigenvalues from small to large.

3.
$$\beta_R = - \frac{\bar{x}_R^T A d_{R-1}}{d_{R-1}^T A d_{R-1}}$$

Recall that

$$\bar{x}_R = \bar{x}_{R-1} - \alpha_{R-1} A d_{R-1}, \text{ where } \alpha_{R-1} = \frac{d_{R-1}^T \bar{x}_{R-1}}{d_{R-1}^T A d_{R-1}}$$

$$\Rightarrow A d_{R-1} = \frac{\bar{x}_{R-1} - \bar{x}_R}{\alpha_{R-1}} = \frac{d_{R-1}^T A d_{R-1}}{d_{R-1}^T \bar{x}_{R-1}}$$

$$\Rightarrow \beta_R = - \frac{\bar{x}_R^T (\bar{x}_{R-1} - \bar{x}_R)}{d_{R-1}^T A d_{R-1}}$$

$$= \frac{\bar{x}_R^T (\bar{x}_R - \bar{x}_{R-1})}{d_{R-1}^T \bar{x}_{R-1}}$$

Since $d_{R-1} = \bar{x}_{R-1} + \beta_{R-1} \underbrace{d_{R-2}}_{\in V_{R-1}}$,

and $\bar{x}_{R-1}^T V = 0$ for all $v \in V_{R-1}$, we see that

$$d_{R-1}^T \bar{x}_{R-1} = \bar{x}_{R-1}^T \bar{x}_{R-1},$$

and therefore

$$\beta_R = \frac{\bar{x}_R^T (\bar{x}_R - \bar{x}_{R-1})}{\bar{x}_{R-1}^T \bar{x}_{R-1}} \equiv \beta_R^{FR}$$

Similarly $\bar{x}_{R-1} \in V_R$ and $\bar{x}_R^T V = 0$ for all $v \in V_R$,

so that

$$\beta_R = \frac{\bar{x}_R^T \bar{x}_R}{\bar{x}_{R-1}^T \bar{x}_{R-1}} \equiv \beta_R^{FR}$$