

RUE - Final exam solutions - Fall US

(a) Recall that $D|x| = \frac{x}{|x|}$ and $D \cdot x = n$.

$$Dh = 2x |x-x_0|^{-n} + (|x|^2 - R^2)^{-n} \frac{x-x_0}{|x-x_0|^{n+2}}$$

$$\Delta h = D \cdot Dh = 2n |x-x_0|^{-n} + 2x \cdot (-n) \frac{x-x_0}{|x-x_0|^{n+2}} + 2x \cdot (-n) \frac{x-x_0}{|x-x_0|^{n+2}} - n(|x|^2 - R^2)^{-n} \frac{n}{|x-x_0|^{n+2}} + n(n+2)(|x|^2 - R^2)^{-1} \frac{1}{|x-x_0|^{n+2}}$$

$$= \frac{2n}{|x-x_0|^{n+2}} \underbrace{\left[|x-x_0|^2 - 2x \cdot (x-x_0) + (|x|^2 - R^2) \right]}_{=0}$$

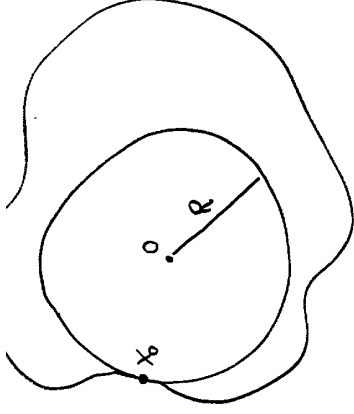
$$= 0 \quad \text{if } x \neq x_0$$

Note: The first term of h is a multiple of the Poisson kernel for the disk, see Evans.

(b) Choose R such that $B(0, R)$ is the largest open ball centered at the origin contained in U (since U is open, such R exists). Then $\partial B(0, R) \cap \partial U$ is non-empty and we can

choose

$$x_0 \in \partial B(0, R) \cap \partial U.$$



now set $U = h$ with x_0 and $R = |x_0|$ as above and note that

$$h(x) > 0 \quad \text{if } |x| > R \quad (*)$$

Since h is harmonic in U ,

$$\begin{aligned} 0 = h(0) &= \int_U h(x) dx \\ &= \int_U h(x) dx \\ &= \underbrace{\int_{B(0, R)} h(x) dx}_{= |B(0, R)| h(0)} + \int_{U \setminus B(0, R)} h(x) dx \\ &= 0 \end{aligned}$$

as h is harmonic on $B(0, R)$

so the last term is strictly positive due to $(*)$ unless $U = B(0, R)$.

□

2. Let u, v be two such solutions and set $w = u - v$. Then

$$w_t = \Delta w - u^2 + v^2 \\ = \Delta w - w(u+v)$$

Now multiply with w and integrate:

$$\int_{\bar{U}} w w_t = \int_{\bar{U}} w \Delta w - \int_{\bar{U}} w^2 (u+v) \\ \Rightarrow \frac{1}{2} \frac{d}{dt} \int_{\bar{U}} w^2 dx = - \int_{\bar{U}} |Dw|^2 dx - \int_{\bar{U}} w^2 (u+v) dx \quad \text{as } w=0 \text{ on } \partial \bar{U}$$

$$\Rightarrow \frac{d}{dt} \int_{\bar{U}} w^2 dx \leq \underbrace{2(\|u\|_{\infty}^2 + \|v\|_{\infty}^2)}_{\leq c < \infty} \int_{\bar{U}} w^2 dx$$

$$\Rightarrow \int_{\bar{U}} w^2(t) dx \leq \underbrace{\int_{\bar{U}} w^2(0) dx}_{=0} e^{cT}$$

$$\Rightarrow w \equiv 0 \text{ on } \bar{U}_T.$$

(4)

3(a) This can be verified by direct differentiation; nothing $t=0$ in the expressions for u and u_t recovers the initial conditions.

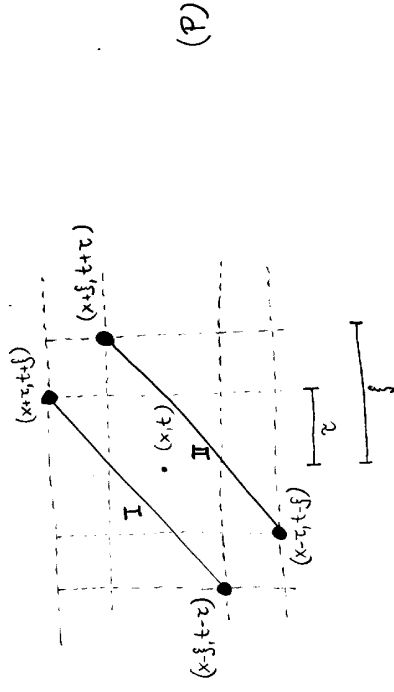
A constructive derivation is given in Evans (and in class).

(b) Let $v = u_t + u_x$. Then, if u satisfies the wave equation,

$$0 = u_{tt} - u_{xx} = v_t - v_x \Rightarrow v = a(x+t)$$

for some function a .

$$\Rightarrow u_t + u_x = a(x+t) \quad (*)$$



Lines I and II are both characteristic lines of (*).

To integrate along I, note that, from (*),

$$\frac{d}{ds} u(x-\xi+s, t-\tau+s) = a(x-\xi+t-\tau+2s)$$

$$\Rightarrow u(x+\tau, t+\xi) - u(x-\xi, t-\tau) = \int_0^{\tau+\xi} a(x-\xi+t-\tau+2s) ds$$

Similarly, to integrate along II, we note

$$\frac{d}{ds} u(x-\tau+s, t-\xi+s) = a(x-\tau+t-\xi+2s)$$

$$\Rightarrow u(x+\xi, t+\tau) - u(x-\tau, t-\xi) = \int_0^{\tau+\xi} a(x-\tau+t-\xi+2s) ds$$

Since the two integrals above are equal,

$$u(x+\tau, t+\xi) + u(x+\xi, t+\tau) = u(x-\xi, t-\tau) + u(x-\tau, t-\xi). \quad (**)$$

The converse is proved by differentiating (***) with respect to ξ twice, then setting $\xi = \tau = 0$.

Remark: It is known that if u is a solution to the wave equation, then

$$u(x, t) = f_1(x+t) + f_2(x-t) \quad (***)$$

Then (**) can be verified by direct substitution of the respective arguments of u into (***).

The difficulty here lies in the fact that (a) proves (***) only in the absence of boundaries. There are two ways to proceed:

(i) Prove (***) in general by careful integration along characteristics - this will be similar to the direct proof of (**) given above.

(ii) Note that when $\tau = 0$, figure (P) is a square



Thus, the entire square can be seen as the cone of dependence of the initial value problem with initial data on the line $[x-\xi, x+\xi] \times \{t_0=t\}$, both forward and backward in time. So, no boundaries are involved so that (a) directly applies and proves (***).

(+)

Now, to prove (***) on a more general polygon (P), tile the polygon with a countable number of squares of type (S) and obtain (***) in the limit.

(c) First obtain u in the closed region A via (a). Due to the finite speed of propagation, this region is not influenced by data outside of $[a, b] \times \{t=0\}$, so that (a) applies.

Then fill B and C using (**), finally D, again via (**) up to $t = b - a$. Now re-initialize to go beyond $t = b - a$.

4. So long as u is a smooth solution, it is determined by the characteristic relation

$$u(x + g(x)t, t) = g'(x) \quad (*)$$

where $\xi(t) = x + g(x)t$ is the characteristic line starting at location x when $t = 0$.

Differentiating (*) with respect to x gives

$$u_x(\xi(t), t) (1 + g'(x)t) = g''(x)$$

$$\Rightarrow u_x(\xi(t), t) = \frac{g''(x)}{1 + g'(x)t}$$

Thus, a shock occurs at $(\xi(t), t)$ if $1 + g'(x)t = 0$, so the first shock occurs on the characteristic line originating at location x where g' is most negative. This is a point of inflection.

$$5. \int_U |Du|^2 dx = \underbrace{\int_U u \cdot Du}_{=0} ds + \int_U \Delta u du = \underbrace{\int_U \nabla dx}_{=0} \left(\int_U \Delta u dx \right)^{\frac{1}{2}}$$