

II.2 Classification for dim 1 or 2

Def.: Let (L_1, g_1) and (L_2, g_2) be inner product spaces.

A linear isomorphism $f: L_1 \rightarrow L_2$ is called **isometry** if

$$g_1(l, l') = g_2(f(l), f(l')) \quad \forall l, l' \in L_1.$$

(L_1, g_1) and (L_2, g_2) are called **isometric** if there is an isometry for them.

next: • classify spaces up to isometry

• want: $L = \bigoplus_{i=1}^m L_i$ with orthogonal L_i ($\dim L_i = 1$ for orth. and Hermitian,
 $\dim L_i = 1$ or 2 for symplectic)

\Rightarrow study $\dim L = 1$ or 2 first

Different cases:

1d orthogonal over \mathbb{R} :

a) $g = 0$ (degenerate)

\hookrightarrow null

b) isometric to $g(x, y) = xy$ (x and y coordinates in some basis)

\hookrightarrow positive (since $g(x, x) > 0$ for $x \neq 0$)

(non-degenerate)

c) isometric to $g(x, y) = -xy$ (non-degenerate)

\hookrightarrow negative

Proof: choose any $l \in L$, if $g(l, l) = 0 \Rightarrow g(xl, l) = 0 \Rightarrow g = 0$

otherwise $g(l, l) \neq 0$, call $g(l, l) = a$, so $g(xl, yl) = axy$

basis change $l \mapsto \frac{1}{\sqrt{|a|}} l$

$$\Rightarrow g\left(x \frac{l}{\sqrt{|a|}}, y \frac{l}{\sqrt{|a|}}\right) = \frac{a}{|a|} xy = \begin{cases} xy, & a > 0 \\ -xy, & a < 0 \end{cases}$$

Id symmetric over \mathbb{C} :

a) $g = 0$

b) $g(x, y) = xy$

Proof: here we can do basis change $l \mapsto \frac{1}{\sqrt{a}} l$

Id Hermitian (over \mathbb{C}):

a) $g = 0$

b) $g(x, y) = x\bar{y}$

c) $g(x, y) = -x\bar{y}$

Proof: if $g(l, l) = 0 \Rightarrow g = 0$ as before

otherwise $0 \neq \underset{(x \neq 0)}{g(xl, xl)} = |x|^2 \underbrace{g(l, l)}_{= e^{i\theta} \text{ classifies } g}$

but $g(l, l) = \overline{g(l, l)}$, so $g(l, l) = \pm 1$

1d symplectic (over $\mathbb{Q}, \mathbb{R}, \mathbb{C}$ (ingen.: characteristic $\neq 2$)):

a) $g = 0$

Proof: $g(l, l) = -g(l, l) \Rightarrow 2g(l, l) = 0 \Rightarrow g(l, l) = 0$

$$g(xl, yl) = xy g(l, l) = 0$$

2d symplectic:

a) $g = 0$

b) $g(x_1 l_1 + x_2 l_2, y_1 l_1 + y_2 l_2) = x_1 y_2 - x_2 y_1$ in some basis $\{l_1, l_2\}$

note: Gram matrix $G = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$

Proof: \bullet g degenerate

$\hookrightarrow \exists l \neq 0$ s.t. $g(l, m) = 0 \forall m \in L$ (*)

extend to basis $\{l, l'\}$

$$\Rightarrow g(x_1 l + x_2 l', y_1 l + y_2 l')$$

$$= x_1 y_1 \underbrace{g(l, l)}_{=0 \text{ as before}} + x_1 y_2 \underbrace{g(l, l')}_{=0 (*)} + x_2 y_1 \underbrace{g(l', l)}_{=-g(l, l')=0 (*)} + x_2 y_2 \underbrace{g(l', l')}_{=0}$$

\bullet g non-degenerate

$\hookrightarrow \exists \tilde{l}_1, l_2$ s.t. $g(\tilde{l}_1, l_2) = \alpha \neq 0$, or, for $l_1 = \frac{\tilde{l}_1}{\alpha}$, $g(l_1, l_2) = 1$

suppose $l_1 = c l_2 \Rightarrow g(l_1, l_2) = g(c l_2, l_2) = c g(l_2, l_2) = 0$,
so l_1 and l_2 are linearly independent

$$\Rightarrow \text{as above: } g(x_1 e_1 + x_2 e_2, y_1 e_1 + y_2 e_2)$$

$$= x_1 y_1 \underbrace{g(e_1, e_1)}_{=0} + x_1 y_2 \underbrace{g(e_1, e_2)}_{=1} + x_2 y_1 \underbrace{g(e_2, e_1)}_{=-g(e_1, e_2)=-1} + x_2 y_2 \underbrace{g(e_2, e_2)}_{=0}$$

II.3 General Classification

Def.: A subspace $L_0 \subset L$ is called

- non-degenerate if $g|_{L_0}$ is non-degenerate
- isotropic if $g|_{L_0} = 0$

Ex.: $(\mathbb{R}^2, g(\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}, \begin{pmatrix} y_1 \\ y_2 \end{pmatrix})) = x_1 y_1 - x_2 y_2$

↳ $\text{span}\left\{\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right\}$ non-degenerate

↳ $\text{span}\left\{\begin{pmatrix} 1 \\ 1 \end{pmatrix}\right\}$ isotropic

Def.: The orthogonal complement L_0^\perp of $L_0 \subset L$ is

$$L_0^\perp := \{e \in L : g(e_0, e) = 0 \text{ for all } e_0 \in L_0\} \subset L$$