

Recall: \bullet $F: G \rightarrow H$ Lie group homomorphism: $F(xy) = F(x)F(y) \quad \forall x, y \in G$

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\bullet subgroup $H < G$ is called normal if $C_g(H) = H \quad \forall g \in G$ ($C_g(H) = gHg^{-1}$)

Thm.: Every Lie group homomorphism has constant rank.

Proof: use isomorphism property and chain rule, HW

basic properties of Lie groups:

Proposition: Let G° be the identity component of G (the connected component containing the identity). Then G° is a Lie group, $\dim G^\circ = \dim G$, and G° is a normal subgroup of G .

Proof: HW

Def.: Let $g \in G$, G Lie group, then the left and right translations $L_g, R_g: G \rightarrow G$ are defined as $L_g(h) = gh$, $R_g(h) = hg$.

Proposition: L_g and R_g are diffeomorphisms.

Proof: smooth as composition of smooth maps, $L_{g^{-1}}, R_{g^{-1}}$ smooth inverses. \square

In some later class: \bullet $O(n)$, $SO(n)$, $U(n)$, $SU(n)$ as Lie groups

\bullet representation theory: representation = Lie group homomorphism $G \rightarrow GL(V)$

(e.g., $\Psi(x)$ solution to a translation or rotation invariant eq.,

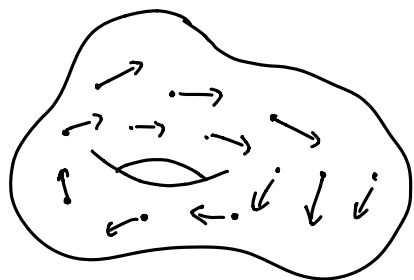
$\Psi \in$ some vector space (also function spaces, Hilbert spaces)

$\Rightarrow \Psi(Rx)$, $R \in G$ is a different solution

$\Psi(Rx) = \underbrace{\Pi(R)}_{\text{representation}} \Psi(x) \quad \Rightarrow$ important research topic

5. Vector Fields and Differential Forms

5.1 Vector Fields



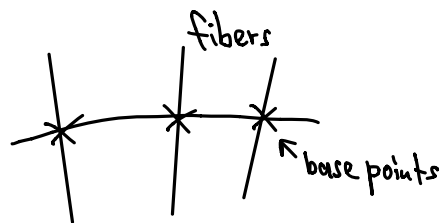
attach vector to each $p \in M$
 \downarrow
 $\in T_p M$

Def.: Let M be a smooth manifold, then the tangent bundle is def. as

$$TM := \bigsqcup_{p \in M} T_p M = \{ (p, v) : p \in M, v \in T_p M \}$$

disjoint union $\left(= \bigcup_{p \in M} T_p M \right)$

Note: • projection $\pi: TM \rightarrow M, \pi(p, v) = p = \text{base point}$
 $\pi^{-1}(p)$ called fiber



• simple case: $T\mathbb{R}^n = \bigsqcup_{a \in \mathbb{R}^n} T_a \mathbb{R}^n \cong \bigsqcup_{a \in \mathbb{R}^n} \{a\} \times \mathbb{R}^n = \mathbb{R}^n \times \mathbb{R}^n$

but usually no canonical identification of different $T_p M$'s

Proposition: Let M be a smooth n -manifold, then TM has a natural topology and smooth structure that make it into a $2n$ -dim. smooth manifold. Furthermore, the projection π is smooth.

Proof idea: • take chart $(U, \varphi), p \in U$

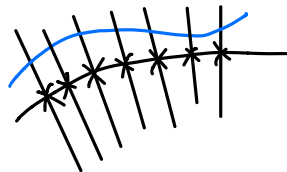
• def. $\tilde{\varphi}: \underbrace{\pi^{-1}(U)}_{TM} \rightarrow \mathbb{R}^{2n}, \tilde{\varphi}(p, v) = \left(\varphi(p), \overbrace{d\varphi_p}^{T_p M \rightarrow T_{\varphi(p)} \mathbb{R}^n \cong \mathbb{R}^n}(v) \right) \in \underbrace{\varphi(U)}_{\mathbb{R}^n} \times \mathbb{R}^n$

• smoothness of transition maps can be checked □

Def.: A smooth vector field is a smooth map $X: M \rightarrow TM$, s.t. $X(p) \in T_p M \forall p \in M$

(i.e., $\pi \circ X = \text{id}_M$).

note: X is called section of the map $\pi: TM \rightarrow M$



Ex.: \cdot zero section $X(p) = 0_{T_p M}$, not a constant map ($0_{T_p M}$ can vary for different p)

\cdot open $U \subset \mathbb{R}^n$, $T_p U \cong \mathbb{R}^n$, def. vector fields $\frac{\partial}{\partial x^i}(p) = e_i$ ($e_i = i$ -th canonical basis vector of \mathbb{R}^n)

$\Rightarrow \frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^n}$ basis of $T_p U \forall p \in U$

any vector field can be written as $X(p) = \sum_{i=1}^n f^i(p) \frac{\partial}{\partial x^i}(p)$, f^i smooth