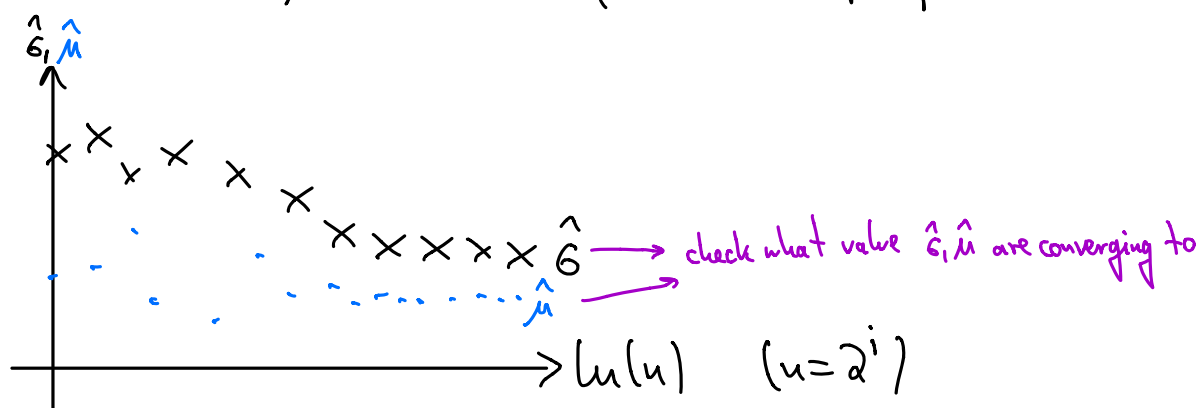
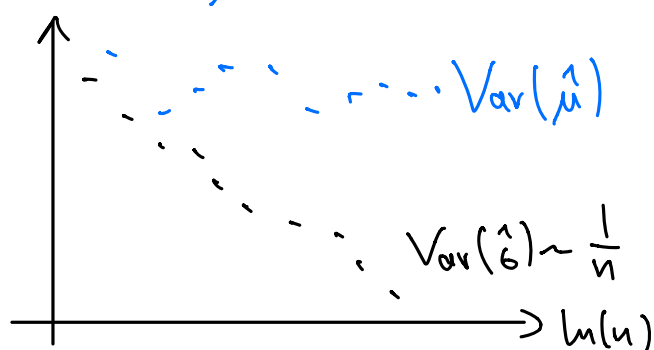


Homework:

a) one realization of GBM, size 2^k then estimate $\hat{\mu}, \hat{\sigma}$ for every 2^i -th sample point, $i=0, \dots, k-1$ 

python: "semilogx(...)" for plot with logarithmic x-axis

b) ensemble of GBMs with some parameters

 $\hookrightarrow \text{Var}(\hat{\sigma}), \text{Var}(\hat{\mu})$ $\ln \text{Var}(\hat{\sigma}), \ln \text{Var}(\hat{\mu})$ \uparrow ensemble variance

c) "Backtracking"

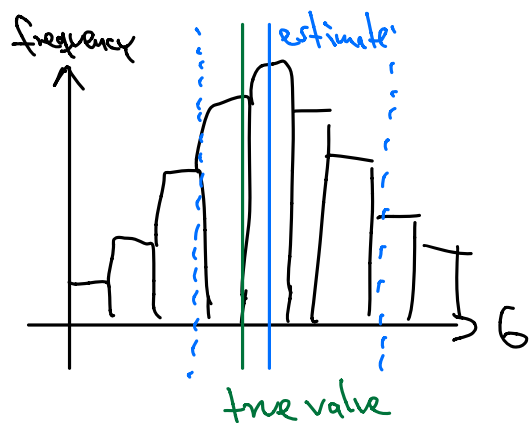
• given a single time series from part a) \rightarrow compute $\hat{\mu}, \hat{\sigma}$

- generate ensemble of GBMs with these parameters

- compute $\text{Var}(\hat{\mu}), \text{Var}(\hat{\sigma})$

=> test how reliable estimate was

python: `hist(sigma-distribution, number of bins, histtype = 'stepfilled')`



← very thin for σ
but wide for μ →

d), e), f) consider some noise sources:

- periodic noise: $S_{\text{per}} = S + c, \sqrt{\Delta t} \overset{\leftarrow \text{GBM}}{\sin(2\pi f \text{ arange}(N+1))}$

- Gaussian noise: $S_{\text{Gauss}} = S + c, \sqrt{\Delta t} \text{ normal}(0, 1, N+1)$

- how does the noise change estimates for $\hat{\mu}, \hat{\sigma}$?

- normality?

- independence?