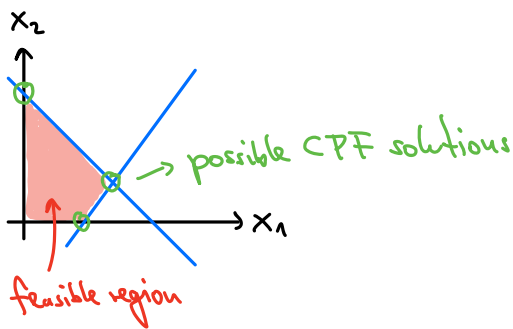


Last time: standard form of LP problems:

- minimize $z = c^T x$
- constraints: $Ax = b$
- $x \geq 0$

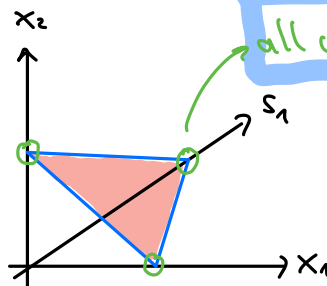
How does the feasible region look like?

• in our first examples (not standard form): polygon



Intuition: if there is an optimal solution, there is at least one which is CPF.

• in standard form:



all corner points are basic feasible solutions

at least one component is 0

Intuition: if there is an optimal solution, at least one should be basic.

Last time: with Gaussian elimination we can find basic solutions:

these are the particular solutions to $Ax = b$ with $x_j = 0$ for $j \notin B$

B = set of columns with pivots

Let us now prove our intuition from above:

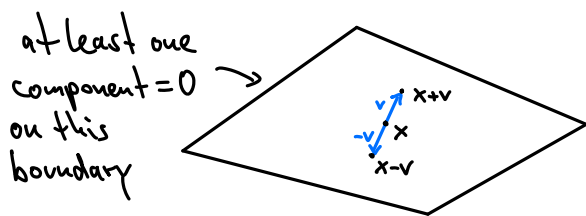
Theorem: If a standard form LP problem has optimal solutions, then there is an optimal basic solution (i.e., an optimal solution that is a vertex/corner of the feasible region).

Proof: We suppose x is an optimal solution which is not basic.

Let us assume that all components of x are non-zero (otherwise we disregard/delete the 0 components, which does not change the problem).
 i.e., we are not already at the boundary

Idea: Now we shift x without changing the value of the objective function until we reach a basic solution ("hit the boundary").

Since $Ax=b$ is a linear constraint and $x>0$, there must be at least one direction vector $v \neq 0$, so that $x+v$ and $x-v$ are still feasible.



We have: • $A(x+v)=b \Rightarrow Ax + Av = b$, and since $Ax=b$, we get $Av=0$
 $= c^T x + c^T v$

• since x is optimal: $c^T x \leq c^T(x+v)$, i.e., $c^T v \geq 0$

$c^T x \leq c^T(x-v)$, i.e., $-c^T v \geq 0 \Rightarrow c^T v \leq 0$

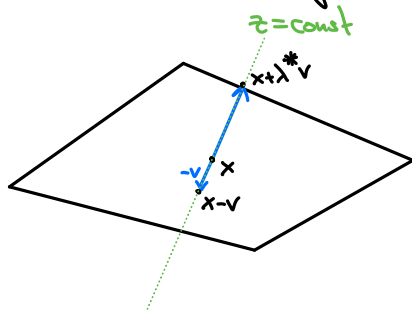
$\Rightarrow c^T v = 0$ ($x \pm v$ does not change value of objective function!)

Now let v have at least one negative component (otherwise take $-v$ instead of v).

↳ this is to make sure we actually go towards a corner

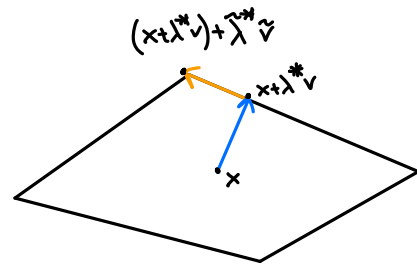
Then $x + \lambda v$ for $\lambda \in [0, 1]$ is feasible and $c^T(x + \lambda v) = c^T x + \lambda \underbrace{c^T v}_{=0} = c^T x$, so $x + \lambda v$ is also optimal.

Now increase λ : at some value $\lambda = \lambda^*$, one component of $x + \lambda v$ will change sign from $+$ to $-$, thus leaving the feasible region.



$\Rightarrow x + \lambda^* v$ is still feasible and optimal, and has at least one component $= 0$.

Finally, we repeat this until solution is basic.



Conclusion: We need to check only basic feasible solutions. □