Calculus and Elements of Linear Algebra I Session 24 Prof. Soren Petrat, Dr. Stephan Juricke (based on lecture notes by Marcel Oliver) Jacobs University, Fall 2022 6. Matrices 6.2 Solving systems of linear equations Topic 6.2. A: Systems of linear equations Take the system of linear equations $-x_{2} + 2x_{3} - x_{4} = 1$ This can be written in matrix form as $A \times = \begin{pmatrix} 0 & 1 & 2 & -1 \\ 1 & 0 & 1 & 1 \\ -1 & 1 & 0 & -1 \\ 0 & 2 & 3 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 2 \\ 0 \end{pmatrix} = b$

$$=A = x = b$$
So a system of linear equations is a matrix
equation of the form $A = b$
(also called inhomogeneous equation for $b \neq 0$)
with x the vector of unknowns.
Suppose x and y are two solutions, i.e.
 $A = b$ and $A = b$
Take difference $A = Ay = b - b$

$$= A(x - y) = 0$$
So the difference vector $x - y = v$ between the
solutions satisfies
 $A = 0$
(the homogeneous equation with
night-hand side equal to zero)
Use versa, if v solves $Av = 0$ and
x solves $A = b$, then
 $y = x + \lambda v$ solves $Ay = A(x + \lambda v) = Ax + \lambda Av$
 $= b$

the inhomogeneous equation again. The equation Ax = bThus: has a unique solution iff Av=0has only one solution v=0. (i) (ii) Otherwise: $A \times = b$ (a) may not have a solution at all b) has many solutions that form a line, plane or hyperplane (i.e. n-dimensional plane)

Calculus and Elements of Linear Algebra I Session 24 Prof. Soren Petrat, Dr. Stephan Juricle (based on lecture notes by Marcel Oliver) Jacobs University, Fall 2022 6. Matrices 6.2 Solving systems of linear equations Topic 6.2. A: Systems of linear equations How to solve systems of linear aquations? We can perform elementary row operations on the full system: (a) Re-order rows (i.e. change order of equations)
(b) Multiply rows with a non-zero scalar (i.e. multiply equation by non-zero number) (c) Add a multiple of one row to another (adding/subtracting equations)

()7 \mathcal{O}^{\prime} Example from before: A 6 $\begin{pmatrix} 0 & 1 & 2 & -1 \\ 1 & 0 & 1 & 1 \\ -1 & 1 & 0 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$. 4 2 2 3 -Use augmented matrix (Alb) of all coefficients aij and solutions bi 1000 5 0100 010 0 023-1 0001 left side of night side equations of equations T with I the identity matrix, all entries zero except for ones along the diagonal. The system Ix = 6 corresponds to $\begin{array}{cccc} x_1 & & = \widetilde{b_1} \\ x_2 & & = \widetilde{b_2} & \text{so} & x_1 = \widetilde{b_1}, & x_2 = \widetilde{b_2}, & x_3 = \widetilde{b_3} \\ x_2 & & = \widetilde{b_2} & \text{and} & x_4 = \widetilde{b_1}, \end{array}$

This corresponds to: $x_1 + 2x_q = 9$ x_{1}, x_{2}, x_{3} $x_2 + x_4 = 11$ $x_3 - x_4 = -5$ are leading variables and for x_y : 0 = 0, i.e. free variable. We have only 3 equations left that contain information but still have 4 unknowns. So we can choose x_{4} as we like, e.g. $x_{4} = 0$ $\Rightarrow \omega = \begin{pmatrix} 9 \\ -5 \\ -5 \end{pmatrix}$ is a solution to Ax = b. However, it is not unique, as x_y is free. For different choice of x_y , we get another solution. So we have to find a vector v = 5.t. Av = 0 to find all solutions of the form $x = \omega + \lambda v$, $\lambda \in \mathbb{R}$ Last column of of the A part of \bigoplus gives us that vector by setting x_y to be a free parameter t: $x_y = t$

$$\Rightarrow x_{n} + 2t = 0 \quad \text{setting} \quad x_{y} = t = -1$$

$$x_{2} + t = 0 \quad x_{n} = 2$$

$$x_{3} - t = 0 \quad \Rightarrow \quad x_{2} = -1$$

$$x_{4} - t = 0 \quad x_{3} = -1$$

$$x_{4} = -1$$
This corresponds to that last column, where zero entry is replaced by -1 :
$$\begin{pmatrix} 1 & 0 & 0 & 2 & 9 \\ 0 & 1 & 0 & -1 & -1 \\ 0 & 0 & -1 & -5 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$replacing this by -1$$
This solves $A = 0$, so we get in total:
$$x = \begin{pmatrix} 2n \\ -5 \\ -5 \end{pmatrix} + \lambda \begin{pmatrix} 2n \\ -1 \\ -1 \end{pmatrix} \quad a \text{ line in 4D space.}$$
This equation of the line is not unique, other solutions ore possible but correspond to the same line.
The process of using row operations to find a solution to $A = b$ is called Gaussian elimination
