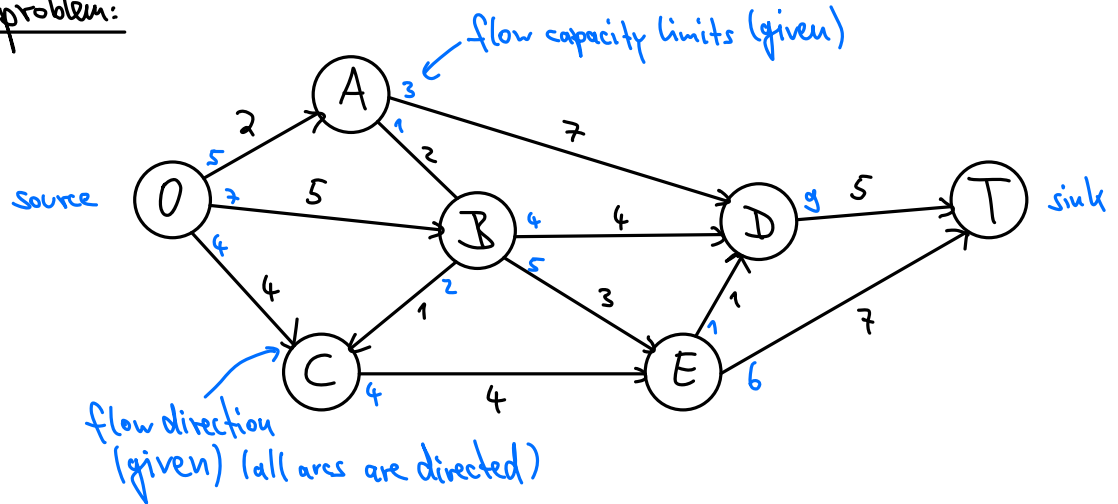


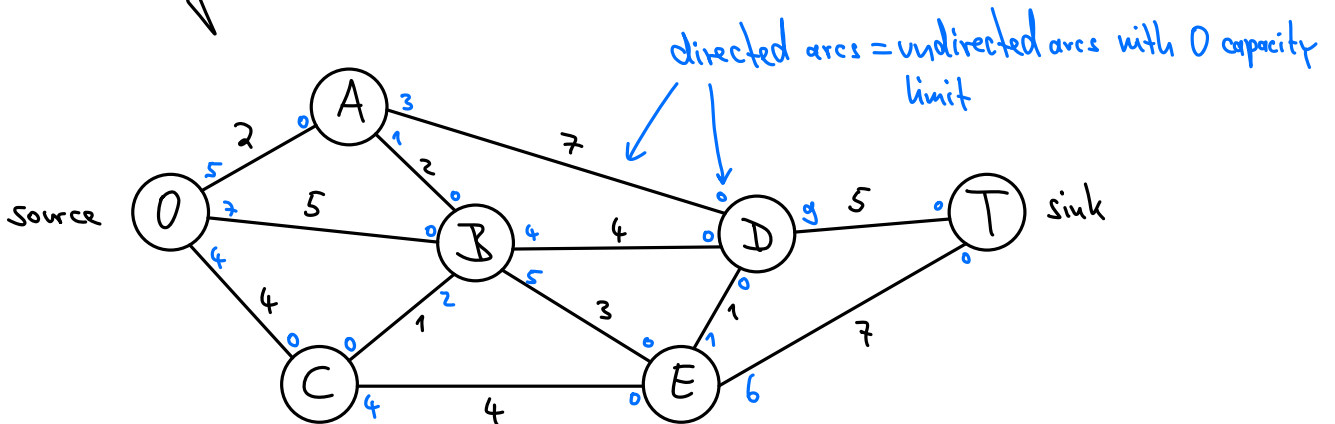
Another problem type is the following:

- Maximum Flow problem:



Objective: maximize flow from source to sink

Augmented Path algorithm: Draw networks as

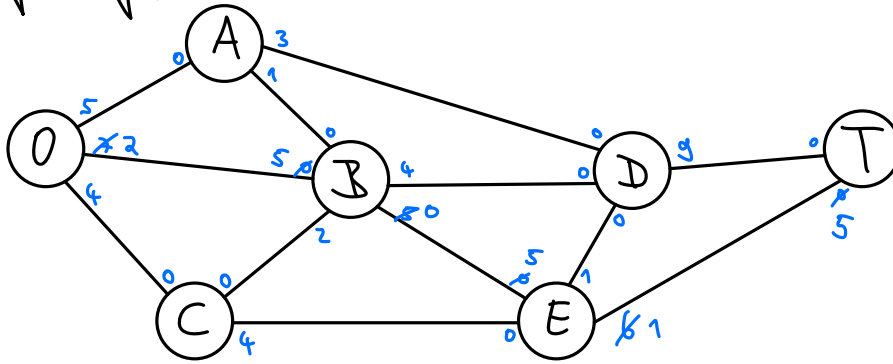


Augmenting path: directed path from source to sink s.t. every arc has strictly positive capacity

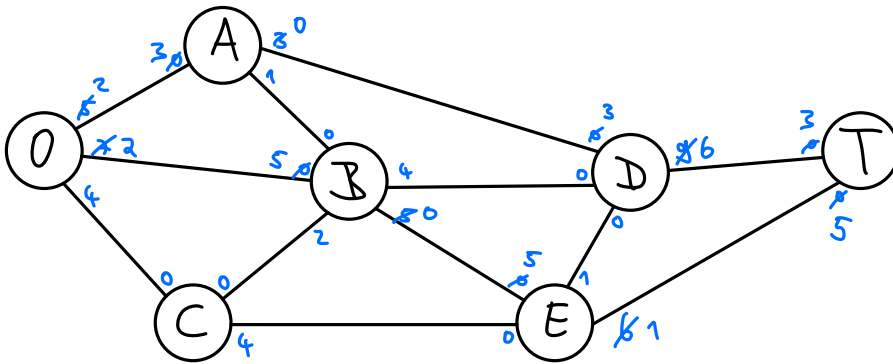
- Now:
- choose an augmenting path
  - increase flow by residual capacity = minimum of all capacities along path
  - change capacity limits accordingly
  - repeat until no augmenting path can be chosen anymore
- in picture: smallest possible number at beginning of arcs

For our example:

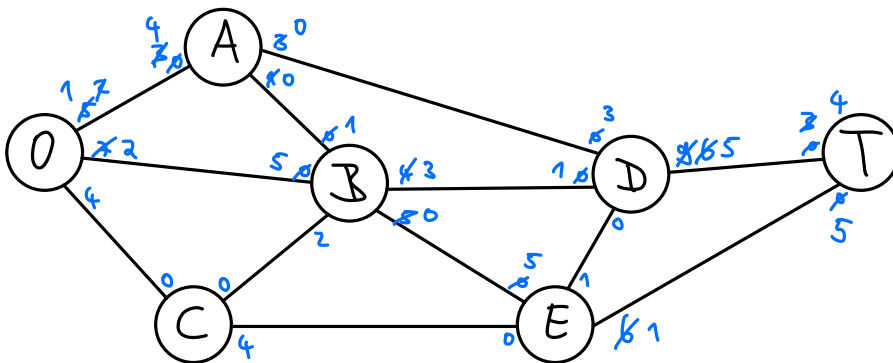
A possible augmenting path is  $O-B-E-T$ : residual capacity: 5 (B-E)



arbitrary next choice:  $O-A-D-T$ : res. cap.: 3 (A-D)



$O-A-B-D-T$ : res. cap.: 1 (A-B)

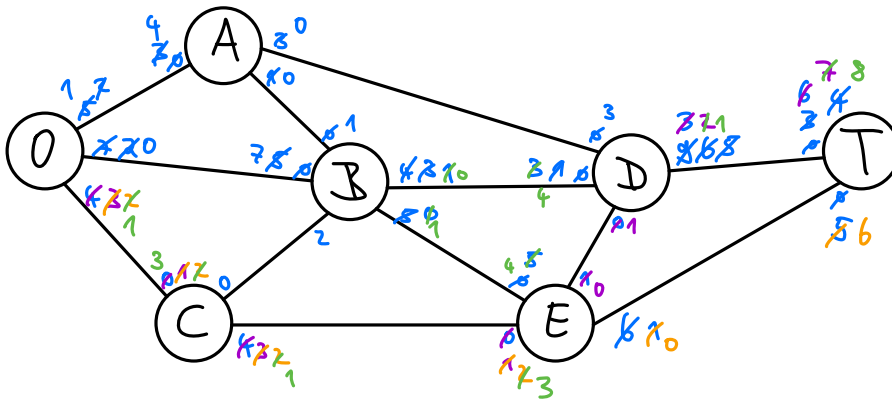


$O-B-D-T$ : res. cap.: 2 (O-B)

$O-C-E-D-T$ : res. cap.: 1 (E-D)

$O-C-E-T$ : res. cap.: 1 (E-T)

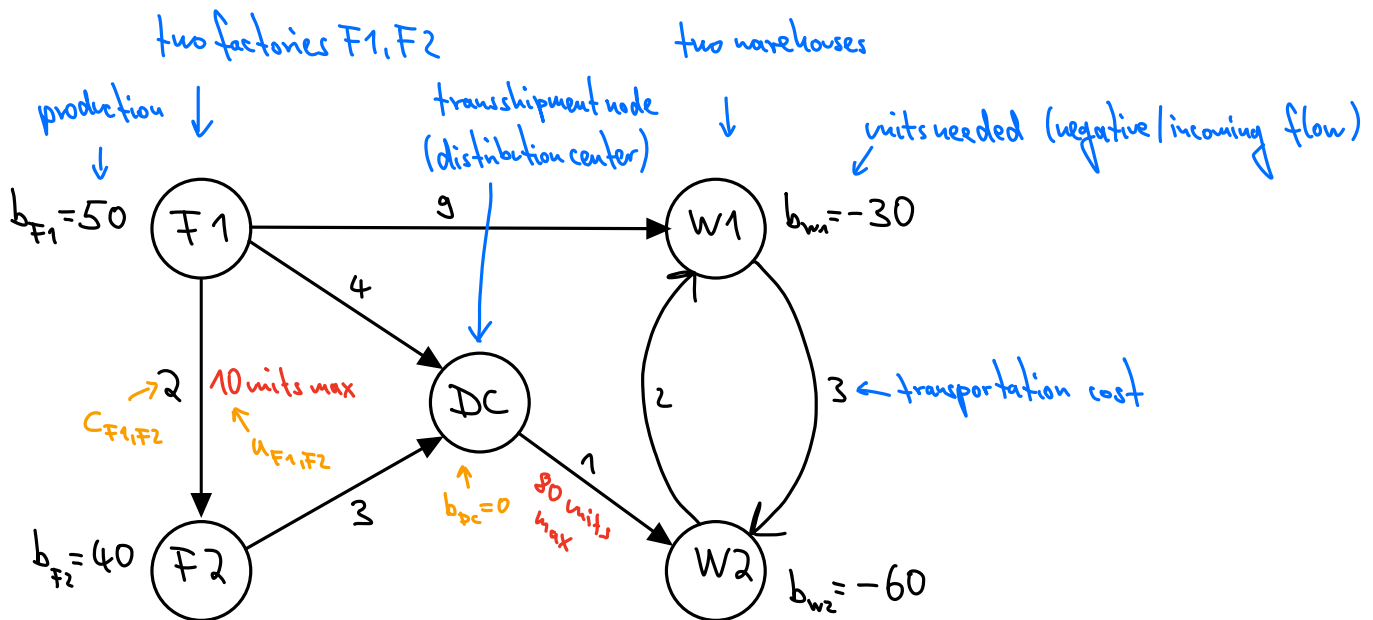
$O-C-E-B-D-T$ : res. cap.: 1 (B-D)



$\Rightarrow$  No more augmenting paths, we have found an optimal solution:  $8+6=14$  trips can be made from  $\textcircled{O}$  to  $\textcircled{T}$  (more details can be read off from final picture).

More generally, all the previous 3 problem types can be formulated as **minimum cost flow problems.**

Example (Hillier, Lieberman Chapters 3.4 and 9.6):



Nodes  $N = \{F1, F2, DC, W1, W2\}$

General formulation:

- nodes  $i \in N$

- directed arcs  $(i, j) \in A$

- $c_{ij}$ : unit cost of transportation on arc  $(i, j)$

- $u_{ij}$ : max. capacity on arc  $(i, j)$

- node constraints •  $b_i > 0$  for supply/source nodes

- $b_i < 0$  for demand/sink nodes

- $b_i = 0$  for transshipment nodes

- $x_{ij}$ : flow from  $i$  to  $j$  (decision variables)