

Recall: we define a surface M by a fct. $f \in C^1(U, \mathbb{R}^3)$ ($U \subset \mathbb{R}^2$ a domain) with normal vector $n := \frac{\partial f}{\partial s} \times \frac{\partial f}{\partial t} \neq 0$. Then we define:

- the surface area $\sigma(M) := \int_U \|n\| dS$,
- for $\phi \in C(M, \mathbb{R})$, the surface integral $\int_M \phi d\sigma := \int_U \phi \circ f \|n\| dS$,
- for $F \in C(M, \mathbb{R}^3)$, the flux integral $\int_M F \cdot \hat{n} d\sigma := \int_U (F \circ f) \cdot n dS$.

Next, we relate flux integrals to volume integrals ("Green's theorem one dimension higher")

3.6 Divergence Theorem

Let us state and discuss the result; we omit proofs.

The divergence thm. holds in any dimension:

Theorem (Divergence Theorem; also called Gauß' Theorem):

Let $D \subset \mathbb{R}^n$ be a domain and let $V \subset D$ s.t.

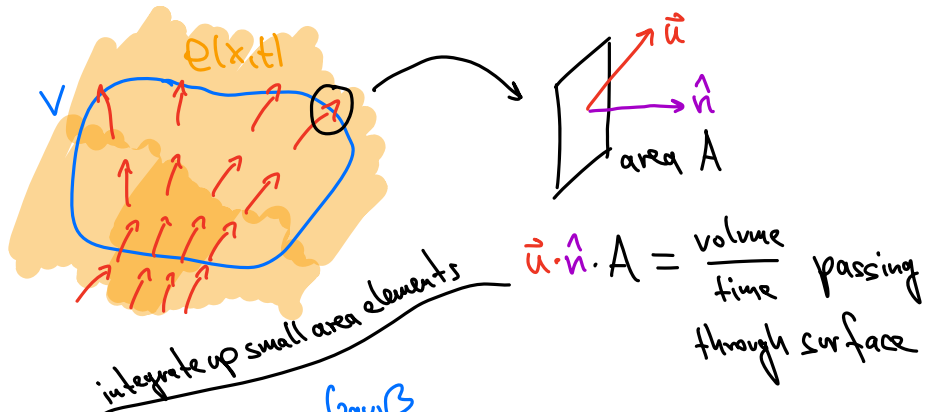
- $\bar{V} \subset D$, and \bar{V} bounded and regular,
- ∂V has non-vanishing piece-wise continuous normal field n ,
- $F \in C^1(V, \mathbb{R}^n)$.

Then $\int_{\partial V} F \cdot \hat{n} d\sigma = \int_V \underbrace{\nabla \cdot F}_{= \operatorname{div} F} dx$, with \hat{n} the outward pointing unit normal vector. ("divergence of F ")

Some interpretation / connection to physics:

Let

- $\rho(x,t)$ = density at point x at time t (e.g., mass density or probability density).
- $m_V(t) = \int_V \rho(x,t) d^3x$ = total mass in domain $V \subset \mathbb{R}^3$.
- $\vec{j}(x,t)$ = flux density (units: $\frac{1}{\text{time} \cdot \text{area}}$) = $\rho(x,t) \cdot \vec{u}(x,t)$, with $\vec{u}(x,t)$ the velocity vector field.



Change of mass in time is $\frac{dm_V(t)}{dt} \stackrel{\text{Gauß}}{=} - \int_{\partial V} \vec{j} \cdot \hat{n} dS \stackrel{\text{by def. of } m_V(t)}{=} - \int_V \text{div} \vec{j} d^3x$

$\stackrel{\text{by def. of } m_V(t)}{=} \int_V \frac{\partial \rho(x,t)}{\partial t} d^3x$

\Rightarrow Since this holds \forall domains V , we have deduced the

$$\text{continuity equation } \frac{\partial \rho}{\partial t} + \text{div} \vec{j} = 0.$$

For heat ("Fourier's law") or other diffusion processes ("Fick's law") we have

$$\vec{j} = -\vec{\nabla} \rho.$$

$$\Rightarrow \text{div} \vec{j} = -\vec{\nabla} \cdot \vec{\nabla} \rho = -\Delta \rho,$$

$\vec{\nabla} \cdot \vec{\nabla} = \frac{\partial^2}{\partial x_1^2} + \dots + \frac{\partial^2}{\partial x_n^2} = \text{Laplace operator}$

which leads to the heat eq. or diffusion eq. $\frac{\partial \rho}{\partial t} = \Delta \rho.$

Another result is a generalization of Green's thm. to our surfaces M .

Theorem (Stokes' theorem):

Let $D \subset \mathbb{R}^3$ be a domain, let $M \subset D$ a smooth surface that is bounded and orientable, and let ∂M have smooth parametrization with orientation anti-clockwise w.r.t. to the normal field of M . Let $F \in C^1(D, \mathbb{R}^3)$.

Then
$$\int_{\partial M} F \cdot dx = \int_M \underbrace{(\nabla \times F) \cdot \hat{n}}_{=: \text{curl } F} d\sigma.$$

Note:

- "Orientable" means that a normal vector field can be chosen consistently (always the case for $M := \text{range } f$).
- For flat surfaces we recover Green's thm.: set $F = \begin{pmatrix} F_1 \\ F_2 \\ 0 \end{pmatrix}$, $\hat{n} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$.

Before we discuss examples, a few interesting implications.

Corollary: With the same notation as in Stokes' thm., assume that M has no boundary. Then $\int_M (\nabla \times F) \cdot \hat{n} d\sigma = 0$ for any $F \in C^1(D, \mathbb{R}^3)$.

Corollary: Let $F \in C^1(D, \mathbb{R}^3)$, $D \subset \mathbb{R}^3$ a simply connected domain. Then F conservative $\Leftrightarrow \nabla \times F = 0$.

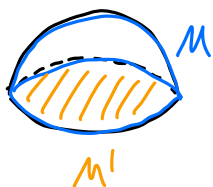
Sketch of proof: " \Rightarrow " If $F = \nabla\phi$, then $\nabla \times F = \nabla \times \nabla\phi = 0$, see homework.

" \Leftarrow " let γ be a closed curve. Under the stated assumptions one can show that there is a "capping surface" M s.t. $\partial M = \gamma$.

Then $\int_{\gamma} F \cdot dx = \int_M (\nabla \times F) \cdot \hat{n} \, d\sigma = 0 \Rightarrow F$ conservative. \square

Examples:

- Let $F(x, y, z) = (x^3, y^3, z^3)$. We compute the flux $\Phi_M(F)$ through the upper hemisphere $M := \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 = R^2, z \geq 0\}$ with radius $R > 0$.



$M' := \{(x, y, 0) \in \mathbb{R}^3 : x^2 + y^2 \leq R^2\}$ the "bottom"

M and M' enclose the volume $V = \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 \leq R^2, z \geq 0\}$.

Then $\Phi_M(F) := \int_M F \cdot \hat{n} \, d\sigma = \int_{M \cup M'} F \cdot \hat{n} \, d\sigma - \int_{M'} F \cdot \hat{n} \, d\sigma$

$\xrightarrow{\text{Gauss}}$ $= \int_V \operatorname{div} F \, d^3x$

$\int_{M'} F \cdot \hat{n} \, d\sigma = F \cdot \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} \Big|_{z=0} = -F_3|_{z=0} = 0$

$= 3 \int_V (x^2 + y^2 + z^2) \, d^3x$

$\xrightarrow{\text{spherical coordinates}}$ $= 3 \int_0^{2\pi} \int_0^{\pi/2} \int_0^R r^2 \cdot r^2 \sin\theta \, dr \, d\theta \, d\varphi$

$= 3 \cdot 2\pi \cdot 1 \cdot \frac{R^5}{5}$

$= \frac{6\pi}{5} R^5$

- Example for Stokes' thm.: see homework

Another application: Maxwell's equations in differential and integral form

- $V \subset \mathbb{R}^3$ a bounded volume with closed boundary ∂V
- $M \subset \mathbb{R}^3$ a surface with closed boundary curve ∂M
- ρ = charge density, $Q = \int_V \rho d^3x$ the total electric charge within V
- \mathbf{J} = el. current density, $I = \int_M \mathbf{J} \cdot \hat{\mathbf{n}} d\sigma$ the el. current passing through M
- \mathbf{E} = electric field, \mathbf{B} = magnetic field
- c = speed of light

Differential version

$$\nabla \cdot \mathbf{E} = 4\pi\rho$$

Gauß
↔

$$\nabla \cdot \mathbf{B} = 0$$

Gauß
↔

$$\nabla \times \mathbf{E} = -\frac{1}{c} \frac{\partial \mathbf{B}}{\partial t}$$

Stokes
↔

$$\nabla \times \mathbf{B} = \frac{1}{c} \left(4\pi\mathbf{J} + \frac{\partial \mathbf{E}}{\partial t} \right)$$

Stokes
↔

Integral version

$$\int_{\partial V} \mathbf{E} \cdot \hat{\mathbf{n}} d\sigma = 4\pi Q$$

$$\int_{\partial V} \mathbf{B} \cdot \hat{\mathbf{n}} d\sigma = 0$$

$$\int_{\partial M} \mathbf{E} \cdot d\mathbf{x} = -\frac{1}{c} \frac{d}{dt} \int_M \mathbf{B} \cdot \hat{\mathbf{n}} d\sigma$$

$$\int_{\partial M} \mathbf{B} \cdot d\mathbf{x} = \frac{1}{c} \left(4\pi I + \frac{d}{dt} \int_M \mathbf{E} \cdot d\sigma \right)$$