

Last time, we introduced the **Hessian** H_f of a function $f: U \rightarrow \mathbb{R}$ ($U \subset \mathbb{R}^n$ open) as

$$(H_f)_{ij} := \frac{\partial^2 f}{\partial x_i \partial x_j}. \text{ For } f \in C^2, \text{ we found } (H_f)_{ij} = (H_f)_{ji} \text{ (Clairaut, Schwarz).}$$

Similar to functions in \mathbb{R} , we can do a Taylor expansion. Let us write it down here up to second order (and for $f: \mathbb{R}^n \rightarrow \mathbb{R}$ only).

Theorem (Taylor, 2nd order): Let $f: U \rightarrow \mathbb{R}$, $U \subset \mathbb{R}^n$ open, $f \in C^2(U)$. Let $x \in U$ and $h \in \mathbb{R}^n$ such that $x+th \in U \forall t \in [0,1]$. Then

$$f(x+h) = f(x) + \mathcal{D}f|_x h + \frac{1}{2} \underbrace{\langle h, H_f(x) h \rangle}_{= h^T H_f(x) h} + r_x(h), \text{ with } \frac{\|r_x(h)\|}{\|h\|^2} \xrightarrow{h \rightarrow 0} 0.$$

Proof: Follows from applying 1-d Taylor to $g(t) := f(x+th)$. \square

The Hessian can be used to determine whether an extremum is a maximum or minimum:

Theorem: Let $f: U \rightarrow \mathbb{R}$, $U \subset \mathbb{R}^n$ open, $f \in C^2(U)$, with $(\mathcal{D}f)(x) = 0$ for some $x \in U$.

Then:

- If $H_f(x)$ is positive definite (i.e., $\langle h, H_f(x) h \rangle > 0 \forall h \in \mathbb{R}^n, h \neq 0$), then f has a **local minimum** at x .
- If $H_f(x)$ is negative definite (i.e., $\langle h, H_f(x) h \rangle < 0 \forall h \in \mathbb{R}^n, h \neq 0$), then f has a **local maximum** at x .

Proof: Follows from the Taylor expansion (making h very small). \square

Note: Since H is symmetric, all eigenvalues are real. Then H is positive definite if and only if all eigenvalues are positive.

A very simple example: $f(x,y) = -x^2 - y^2$.

$$\nabla f = \begin{pmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{pmatrix} = \begin{pmatrix} -2x \\ -2y \end{pmatrix}. \quad \nabla f = 0 \text{ for } (x,y) = (0,0).$$

$$H_f((x,y)=(0,0)) = \begin{pmatrix} -2 & 0 \\ 0 & -2 \end{pmatrix}, \text{ so } H_f(0) \text{ is negative definite.}$$

$\Rightarrow f$ has a maximum at $(0,0)$.

Other examples (see geogebra pictures below):

$$\begin{aligned} \cdot f(x,y) = x^2 - y^2 + 2 &\Rightarrow H_f(0,0) = \begin{pmatrix} 2 & 0 \\ 0 & -2 \end{pmatrix} \Rightarrow \text{saddle point} \\ &(\langle h, H_f h \rangle > 0 \text{ for some } h, \text{ and} \\ &\langle h, H_f h \rangle < 0 \text{ for others}) \end{aligned}$$

$$\begin{aligned} \cdot f(x,y) = x^3 - y^2 + 2 &\Rightarrow H_f(0,0) = \begin{pmatrix} 0 & 0 \\ 0 & -2 \end{pmatrix} \Rightarrow \text{degenerate point} \\ &(\langle h, H_f h \rangle = 0 \text{ for some } h \in \mathbb{R}^n) \end{aligned}$$

$$\begin{aligned} \cdot f(x,y) = y^3 - 3x^2 y + 2 &\Rightarrow H_f(0,0) = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \Rightarrow \text{degenerate point} \\ &(\text{"monkey saddle", see pictures}) \end{aligned}$$

2.3 The Inverse and Implicit Function Theorems

Question: Under which conditions is $f: U \rightarrow \mathbb{R}^n$ ($U \subset \mathbb{R}^n$ open) invertible?

Here f goes from a subset of \mathbb{R}^n into a subset of \mathbb{R}^n .

And: If f is invertible and differentiable, is then f^{-1} also differentiable?
the inverse of f

Reminder:

- $f: X \rightarrow Y$ is called **injective** (or "one-to-one") if $f(x_1) = f(x_2)$ implies $x_1 = x_2$.
(In other words: Given $y \in Y$, then $f(x) = y$ for at most one $x \in X$.)

Ex.: $f: \mathbb{R} \rightarrow \mathbb{R}, x \mapsto e^x$ is injective, but $f: \mathbb{R} \rightarrow \mathbb{R}, x \mapsto x^2$ is not.

- $f: X \rightarrow Y$ is called **surjective** (or "onto") if $\forall y \in Y$ there is an $x \in X$ s.t. $f(x) = y$.

Ex.: $f: \mathbb{R} \rightarrow \mathbb{R}, x \mapsto e^x$ is not surjective, but $f: \mathbb{R} \rightarrow (0, \infty), x \mapsto e^x$ is.

- $f: X \rightarrow Y$ is called **bijective** if it is injective and surjective.

If $f: X \rightarrow Y$ is bijective, then it has an inverse $f^{-1}: Y \rightarrow X$.

(i.e., $f(f^{-1}(y)) = y \quad \forall y \in Y$, or $f^{-1}(f(x)) = x \quad \forall x \in X$.)

From Analysis and Calculus we know the case $n=1$:

If f is continuously differentiable and $f'(p) \neq 0$, then f is invertible in a

neighborhood of p , f^{-1} is continuously differentiable, and $(f^{-1})'(f(p)) = \frac{1}{f'(p)}$.

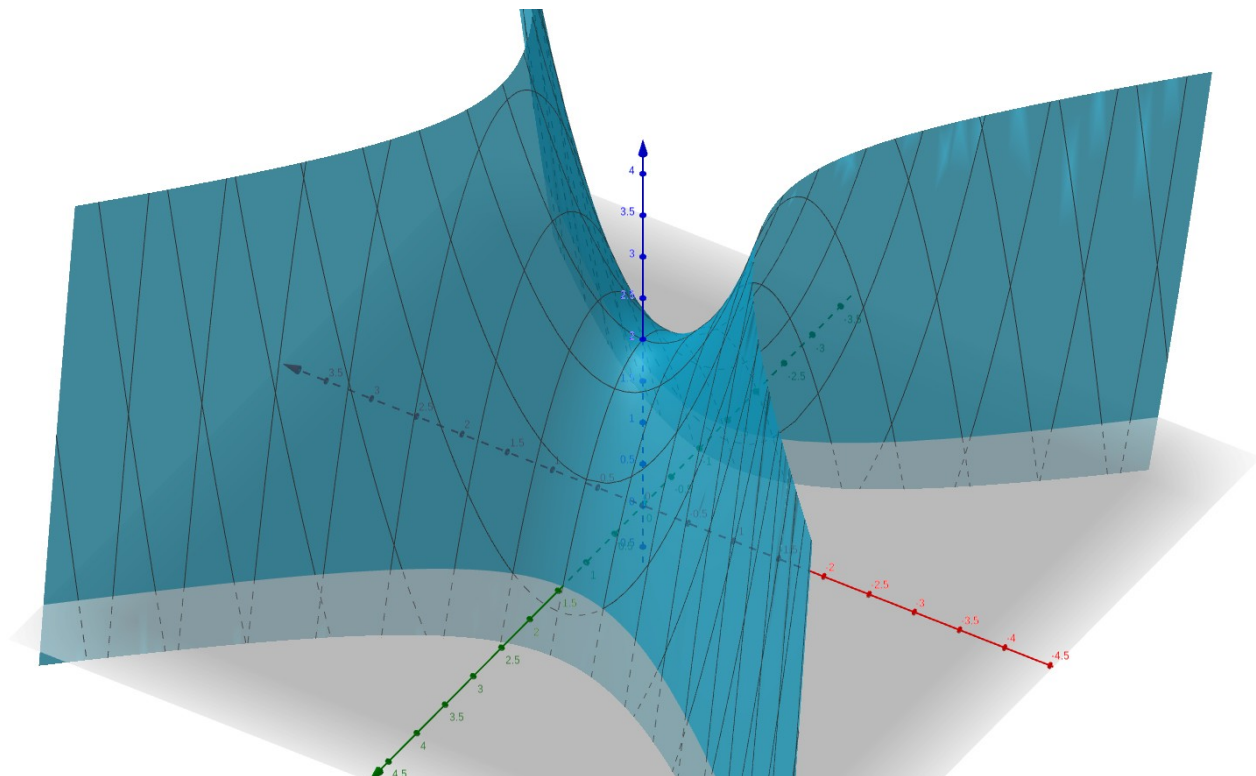
If $f(p) = q$, then $(f^{-1})'(q) = \frac{1}{f'(f^{-1}(q))}$

For $n > 1$: Use linear approximation of f ; then f should be invertible
(in small neighborhood) if Df is invertible.

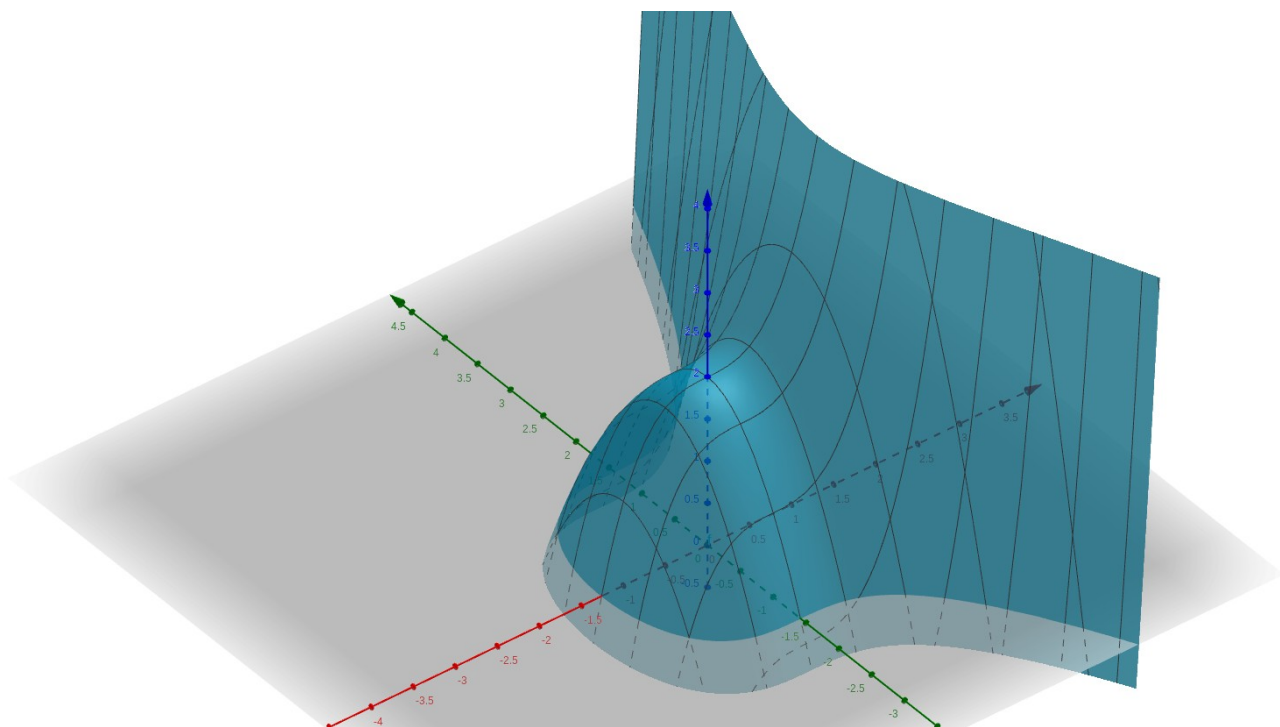
Precise statement: next time.

The following pictures were generated with <https://www.geogebra.org/3d>.

$$f(x, y) = x^2 - y^2 + 2$$



$$f(x, y) = x^3 - y^2 + 2$$



$$f(x, y) = y^3 - 3x^2y + 2$$

(“Monkey Saddle”)

