

Recall:

Theorem: Let $U, V \subset \mathbb{R}^n$ be domains with content, let $\phi: U \rightarrow V$ be a diffeomorphism (i.e., $\phi \in C^1$, ϕ invertible, and $\phi^{-1} \in C^1$). Then, for $f \in \mathcal{R}(V)$ we have

$$\int_V f \, dx = \int_U f(\phi(u)) |\det D\phi(u)| \, du.$$

$$= \int_V f \, ds \qquad = \int_U f \circ \phi |\det D\phi| \, ds$$

Important examples:

Polar coordinates: $\phi(r, \varphi) = \begin{pmatrix} r \cos \varphi \\ r \sin \varphi \end{pmatrix}$

$$\Rightarrow D\phi(r, \varphi) = \begin{pmatrix} \cos \varphi & -r \sin \varphi \\ \sin \varphi & r \cos \varphi \end{pmatrix}, \text{ so } \det(D\phi(r, \varphi)) = r \cos^2 \varphi + r \sin^2 \varphi = r.$$

$$\Rightarrow \int_{\mathbb{B}_R(0)} f(x) \, dx = \int_0^R \int_0^{2\pi} f(r \cos \varphi, r \sin \varphi) \, d\varphi \, r \, dr.$$

• E.g., area of a circle: $\int_{\mathbb{B}_R(0)} 1 \, dx = \int_0^R \int_0^{2\pi} 1 \, d\varphi \, r \, dr = 2\pi \int_0^R r \, dr = \pi R^2.$

• E.g., area of an ellipse $E := \{(x, y) \in \mathbb{R}^2 : \frac{x^2}{a^2} + \frac{y^2}{b^2} \leq 1\}$, given $a, b > 0$.

We can def. $\phi: \mathbb{B}_1(0) \rightarrow E$, $\phi(u, v) = \begin{pmatrix} au \\ bv \end{pmatrix} \Rightarrow D\phi = \begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix} \Rightarrow \det D\phi = ab$

$$\Rightarrow \int_E dx = \int_{\mathbb{B}_1(0)} ab \, d(u, v) = ab\pi.$$

• E.g., Gaussian integral: $I = \int_{-\infty}^{\infty} e^{-x^2} dx$

$$\begin{aligned} \text{Trick: } I^2 &= \int_{-\infty}^{\infty} e^{-x^2} dx \int_{-\infty}^{\infty} e^{-y^2} dy = \int_{\mathbb{R}^2} e^{-x^2-y^2} d(x,y) := \lim_{R \rightarrow \infty} \int_{\mathbb{D}_R(0)} e^{-x^2-y^2} d(x,y) \\ &= \int_0^{\infty} \int_0^{2\pi} e^{-r^2} d\varphi r dr \\ &= 2\pi \int_0^{\infty} \underbrace{e^{-r^2} r}_{= \frac{-1}{2} \left(\frac{d}{dr} e^{-r^2} \right)} dr = -\pi e^{-r^2} \Big|_0^{\infty} = \pi \end{aligned}$$

$$\Rightarrow \int_{-\infty}^{\infty} e^{-x^2} dx = \sqrt{\pi}$$

Other very important coordinates:

• Spherical coordinates: $\Phi(r, \varphi, \theta) = \begin{pmatrix} r \cos \varphi \sin \theta \\ r \sin \varphi \sin \theta \\ r \cos \theta \end{pmatrix}$, $r \geq 0$, $0 \leq \varphi < 2\pi$, $0 \leq \theta \leq \pi$

$$\Rightarrow |\det \Phi| = r^2 \sin \theta$$

• Cylindrical coordinates: $\Phi(\rho, \varphi, z) = \begin{pmatrix} \rho \cos \varphi \\ \rho \sin \varphi \\ z \end{pmatrix}$, $\rho \geq 0$, $0 \leq \varphi < 2\pi$, $z \in \mathbb{R}$

$$\Rightarrow |\det \Phi| = \rho$$

Next: We consider integrals along curves and surfaces and their relation to Riemann integrals and each other. This will lead us to generalizations of the Fundamental Theorem of Calculus. (E.g., $\int_{\text{curve}} F dx$ depends only on endpoints $\gamma(a)$ and $\gamma(b)$. E.g., $\int_D \nabla \cdot \mathbf{b} dS = \int_{\partial D} \mathbf{b} \cdot \mathbf{n} ds$.)

integral over D depends only on ∂D !

Applications: Force fields, electrodynamics, ...

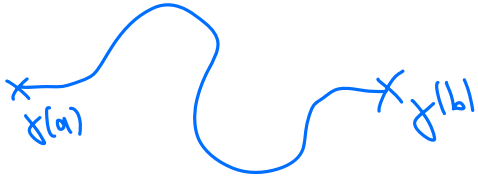
3.3 Line Integrals

We first introduce curves and their length.

Definition:

Any continuous function $\gamma: [a, b] \rightarrow \mathbb{R}^n$ is called an **oriented curve** (or path).

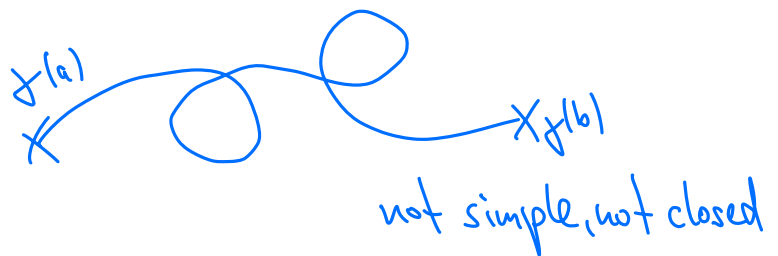
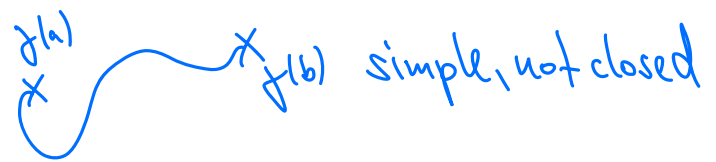
\rightarrow i.e., $\gamma \in C([a, b], \mathbb{R}^n)$



A few important types of curves:

• If $\gamma(a) = \gamma(b)$, the curve is **closed**.

• If $\gamma: [a, b] \rightarrow \mathbb{R}^n$ is injective, the curve is **simple**.



• Two curves γ and ρ are called **equivalent** if there is a continuous, monotonic, increasing h s.t. $\gamma = \rho \circ h$ (i.e., the images of γ and $\rho \circ h$ are the same).

"going through the curve with a different velocity"

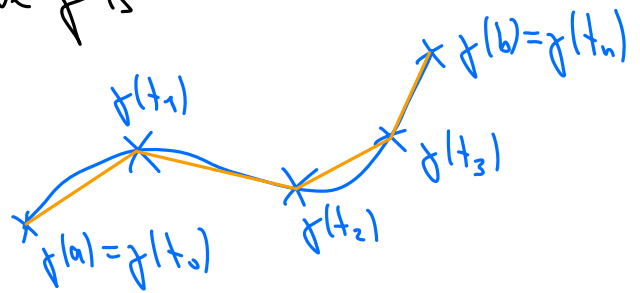
Next: length of a curve (note that it will turn out that not all curves have a length!)

Let \mathcal{T} be a partition of $[a, b]$ with $a = t_0 < t_1 < t_2 < \dots < t_n = b$, and let

$$\lambda(\mathcal{T}) := \max_{i=1, \dots, n} \underbrace{|t_i - t_{i-1}|}_{=: \Delta t_i}$$

Then an approximation to the length of a curve γ is

$$\Lambda(\mathcal{T}, \gamma) := \sum_{i=1}^n \|\gamma(t_i) - \gamma(t_{i-1})\|.$$



length of $\gamma \approx$ sum of lengths of line segments

Definition: The **length of the curve** $\gamma \in C([a, b])$ is defined as

$$\Lambda(\gamma) = \sup_{\mathcal{T}} \Lambda(\mathcal{T}, \gamma).$$

If $\Lambda(\gamma) < \infty$, we call γ **rectifiable** (" γ has length").

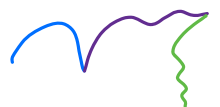
We get a more concrete formula for continuously differentiable curves.

Theorem: let $\gamma \in C^1([a, b])$. Then γ is rectifiable and

$$\Lambda(\gamma) = \int_a^b \|\gamma'(t)\| dt.$$

$$\text{"} \int \|\dot{\gamma}\| = \int \left\| \frac{d\gamma}{dt} \right\| dt \text{"}$$

Note: The theorem is obviously extended to piece-wise C^1 curves.



Proof:

$$" \leq ": \Lambda(\tau, \gamma) = \sum_{i=1}^n \|\gamma(t_i) - \gamma(t_{i-1})\| = \sum_{i=1}^n \left\| \int_{t_{i-1}}^{t_i} \gamma'(t) dt \right\|$$

$$\leq \sum_{i=1}^n \int_{t_{i-1}}^{t_i} \|\gamma'(t)\| dt = \int_a^b \|\gamma'(t)\| dt,$$

$$\text{so also } \Lambda(\gamma) = \sup_{\tau} \Lambda(\tau, \gamma) \leq \int_a^b \|\gamma'(t)\| dt.$$

[Note: the " \geq " direction was not shown in class]

" \geq ": Let $\varepsilon > 0$. We know that γ' is uniformly continuous $\Rightarrow \exists \delta > 0$ s.t.
 $\forall s, t \in [a, b]$ with $|s - t| < \delta$ we have $\|\gamma'(s) - \gamma'(t)\| < \varepsilon$.

Let τ be a partition with $\lambda(\tau) < \delta$.

Then $\|\gamma'(t)\| \leq \|\gamma'(t_i)\| + \varepsilon \quad \forall t \in [t_{i-1}, t_i]$

$$\Rightarrow \int_a^b \|\gamma'(t)\| dt = \sum_{i=1}^n \int_{t_{i-1}}^{t_i} \|\gamma'(t)\| dt \leq \sum_{i=1}^n (\|\gamma'(t_i)\| + \varepsilon) \Delta t_i$$

$$= \sum_{i=1}^n \left(\underbrace{\left\| \int_{t_{i-1}}^{t_i} \gamma'(t_i) dt \right\|}_{\substack{= \int_{t_{i-1}}^{t_i} \gamma'(t_i) dt \\ = \gamma(t_i) - \gamma(t_{i-1})}} + \varepsilon \Delta t_i \right)$$

$$= \int_{t_{i-1}}^{t_i} \gamma'(t_i) dt + \underbrace{\int_{t_{i-1}}^{t_i} (\gamma'(t_i) - \gamma'(t)) dt}_{\leq \varepsilon \text{ in abs. value}}$$

$$\leq \sum_{i=1}^n \left(\underbrace{\left\| \int_{t_{i-1}}^{t_i} \gamma'(t_i) dt \right\|}_{= \gamma(t_i) - \gamma(t_{i-1})} + 2\varepsilon \Delta t_i \right)$$

$$= \gamma(t_i) - \gamma(t_{i-1})$$

$$= \underbrace{\Lambda(\tau, \gamma)}_{\leq \Lambda(\gamma)} + 2\varepsilon(b-a)$$

$$\leq \Lambda(\gamma)$$

Since ε was arbitrary (arbitrarily small), we find $\int_a^b \|\gamma'(t)\| dt \leq \Lambda(\gamma)$. \square

Note that for $f \in C^1$, the length $L(f)$ is independent of the parameterization: If $f = \rho \circ h$, $h \in C^1$ increasing, then

$$\int_a^b \|f'(t)\| dt = \int_a^b \left\| \frac{d}{dt} \rho(h(t)) \right\| dt = \int_a^b \|\rho'(h(t))\| h'(t) dt = \int_{h(a)}^{h(b)} \|\rho'(u)\| du.$$

chain rule substitution

$$(u = h(t) \Rightarrow du = h'(t) dt)$$